

Differential algebraic equations: Mini course 2

Inconsistent initial values and distributional solutions

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Explicit solution formula for regular DAEs

$$E\dot{x} = Ax + Bu \quad (E, A) \stackrel{S, T}{\cong} \left(\begin{bmatrix} I & 0 \\ 0 & N \end{bmatrix}, \begin{bmatrix} J \\ I \end{bmatrix} \right)$$

Definition (Consistency projector, differential/impulsive selector)

$$\Pi_{(E,A)} := T \begin{bmatrix} I & 0 \\ 0 & 0 \end{bmatrix} T^{-1}$$

$$\Pi_{(E,A)}^{\text{diff}} := T \begin{bmatrix} I & 0 \\ 0 & 0 \end{bmatrix} S$$

$$\Pi_{(E,A)}^{\text{imp}} := T \begin{bmatrix} 0 & 0 \\ 0 & I \end{bmatrix} S$$

$$A^{\text{diff}} := \Pi_{(E,A)}^{\text{diff}} A$$

$$B^{\text{diff}} := \Pi_{(E,A)}^{\text{diff}} B$$

$$E^{\text{imp}} := \Pi_{(E,A)}^{\text{imp}} E$$

$$B^{\text{imp}} := \Pi_{(E,A)}^{\text{imp}} B$$

Theorem (Solution formula, cf. TRENN 2012)

(x, u) is a smooth solution of $E\dot{x} = Ax + Bu \iff$

$$x(t) = e^{A^{\text{diff}} t} \Pi_{(E,A)} x(0) + \int_0^t e^{A^{\text{diff}}(t-s)} B^{\text{diff}} u(s) ds - \sum_{i=0}^{\nu-1} (E^{\text{imp}})^i B^{\text{imp}} u^{(i)}(t)$$

Decomposition of solution

$$x(t) = e^{A^{\text{diff}}t} \Pi_{(E,A)} x(0) + \int_0^t e^{A^{\text{diff}}(t-s)} B^{\text{diff}} u(s) ds - \sum_{i=0}^{\nu-1} (E^{\text{imp}})^i B^{\text{imp}} u^{(i)}(t)$$

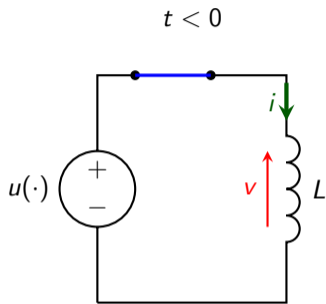
Corollary

x solves $E\dot{x} = Ax + Bu \iff x = x^{\text{diff}} \oplus x^{\text{imp}}$ where

$$\begin{aligned} \dot{x}^{\text{diff}} &= A^{\text{diff}} x^{\text{diff}} + B^{\text{diff}} u, & x^{\text{diff}}(0) &\in \text{im } \Pi_{(E,A)} \\ E^{\text{imp}} \dot{x}^{\text{imp}} &= x^{\text{imp}} + B^{\text{imp}} u \end{aligned}$$

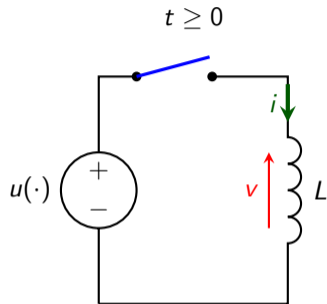
Furthermore $x^{\text{diff}}(t) \in \mathcal{V}^*$ and $x^{\text{imp}}(t) \in \text{im}[B^{\text{imp}}, E^{\text{imp}} B^{\text{imp}}, \dots, (E^{\text{imp}})^{n-1} B^{\text{imp}}] \subseteq \mathcal{W}^*$.

Motivating example



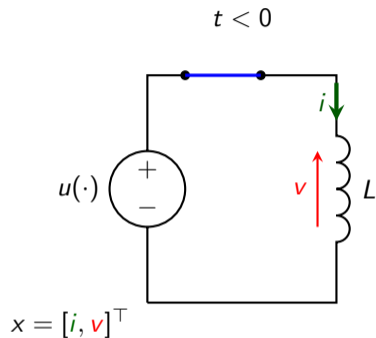
inductivity law:
switch dependent: $0 = v - u$

$$L \frac{d}{dt} i = v$$



$$0 = i$$

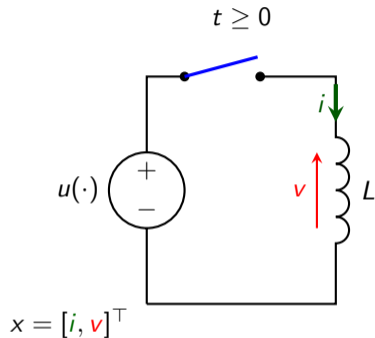
Motivating example



$$\begin{bmatrix} L & 0 \\ 0 & 0 \end{bmatrix} \dot{x} = \begin{bmatrix} 0 & 1 \\ 0 & 1 \end{bmatrix} x + \begin{bmatrix} 0 \\ -1 \end{bmatrix} u$$

→ switched differential-algebraic equation

↷ $x(0^-)$ **not consistent** with open-switch DAE



$$\begin{bmatrix} L & 0 \\ 0 & 0 \end{bmatrix} \dot{x} = \begin{bmatrix} 0 & 1 \\ 1 & 0 \end{bmatrix} x + \begin{bmatrix} 0 \\ 0 \end{bmatrix} u$$

Solution of circuit example

$$t < 0$$

$$v = u$$

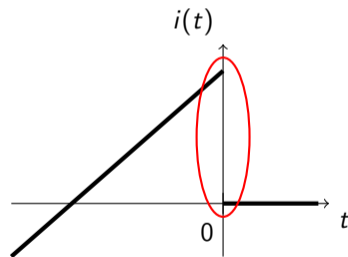
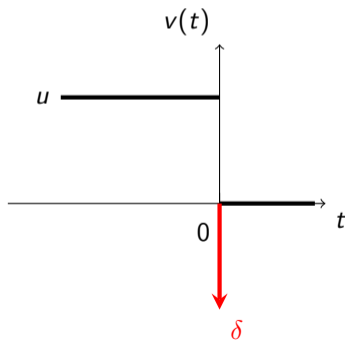
$$L \frac{d}{dt} i = v$$

$$t \geq 0$$

$$i = 0$$

$$v = L \frac{d}{dt} i$$

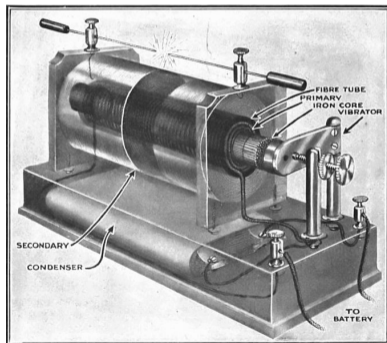
Solution (assume constant input u):



Dirac impulse is “real”

Dirac impulse

Not just a mathematical artifact!



Drawing: Harry Winfield Secor, public domain

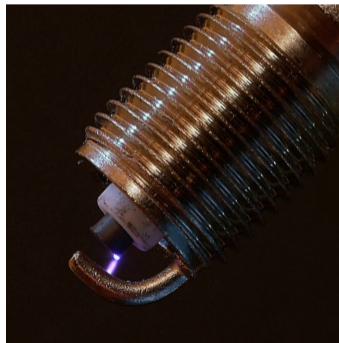


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Distribution theory - basic ideas

Distributions - overview

- ▶ Generalized functions
- ▶ Arbitrarily often differentiable
- ▶ Dirac-Impulse δ is “derivative” of Heaviside step function $\mathbb{1}_{[0,\infty)}$

Two different formal approaches

- 1) Functional analytical: Dual space of the space of test functions (L. Schwartz 1950)
- 2) Axiomatic: Space of all “derivatives” of continuous functions (J. Sebastião e Silva 1954)

Distributions - formal

Definition (Test functions)

$$\mathcal{C}_0^\infty := \{ \varphi : \mathbb{R} \rightarrow \mathbb{R} \mid \varphi \text{ is smooth with compact support} \}$$

Definition (Distributions)

$$\mathbb{D} := \{ D : \mathcal{C}_0^\infty \rightarrow \mathbb{R} \mid D \text{ is linear and continuous} \}$$

Definition (Regular distributions)

$$f \in \mathcal{L}_{1,\text{loc}}(\mathbb{R} \rightarrow \mathbb{R}): \quad f_{\mathbb{D}} : \mathcal{C}_0^\infty \rightarrow \mathbb{R}, \quad \varphi \mapsto \int_{\mathbb{R}} f(t)\varphi(t) dt \in \mathbb{D}$$

Definition (Derivative)

$$D'(\varphi) := -D(\varphi')$$

$$(\mathbb{1}_{[0,\infty)}_{\mathbb{D}})'(\varphi) = -\int_{\mathbb{R}} \mathbb{1}_{[0,\infty)}\varphi' = -\int_0^\infty \varphi' = -(\varphi(\infty) - \varphi(0)) = \varphi(0)$$

Dirac Impulse at $t_0 \in \mathbb{R}$

$$\delta_{t_0} : \mathcal{C}_0^\infty \rightarrow \mathbb{R}, \quad \varphi \mapsto \varphi(t_0)$$

Distributional DAE and ITPs

Distributional solutions

Distributional DAE: $E\dot{X} = AX + BU$, $X \in \mathbb{D}^n$, $U \in \mathbb{D}^m$

- ▶ Classical solution behavior dense in distributional solution behavior
 \rightsquigarrow **essentially no difference** between classical and distributional solutions
- ▶ No differentiability requirements for U (all distributions are “ \mathcal{C}^∞ ”)
- ▶ Initial value problems cannot be formulated, $X(0)$ **not defined**

Initial trajectory problem (ITP)

Given $X^0 \in \mathbb{D}^n$ (initial trajectory) and $U \in \mathbb{D}^m$ find $X \in \mathbb{D}^\ell$ with

$$\begin{aligned} X_{(-\infty,0)} &= X^0_{(-\infty,0)} \\ (E\dot{X})_{[0,\infty)} &= (AX + BU)_{[0,\infty)} \end{aligned} \tag{ITP}$$

Restriction not well defined, cf. TRENN 2021

Restriction of general distributions to interval **not well defined** (actually **not definable**)

Piecewise-smooth distributions

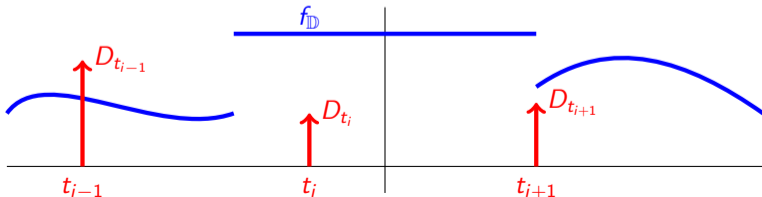
Dilemma

- ▶ Examples indicate presence of **Dirac impulses** in response to inconsistent initial values
- ▶ Inconsistent initials **cannot** be considered for distributions

Define a suitable smaller space:

Definition (Piecewise smooth distributions $\mathbb{D}_{\text{pw}C^\infty}$)

$$\mathbb{D}_{\text{pw}C^\infty} := \left\{ f_{\mathbb{D}} + \sum_{t \in T} D_t \mid \begin{array}{l} f \in C_{\text{pw}}^\infty, T \subseteq \mathbb{R} \text{ locally finite,} \\ \forall t \in T : D_t = \sum_{i=0}^{n_t} a_i^t \delta_t^{(i)} \end{array} \right\}$$



Properties of $\mathbb{D}_{\text{pw}}\mathcal{C}^\infty$

- ▶ $\mathcal{C}_{\text{pw}}^\infty$ “ \subseteq ” $\mathbb{D}_{\text{pw}}\mathcal{C}^\infty$
- ▶ **Closed under differentiation**, i.e. $D \in \mathbb{D}_{\text{pw}}\mathcal{C}^\infty \Rightarrow D' \in \mathbb{D}_{\text{pw}}\mathcal{C}^\infty$
- ▶ **Well defined restriction** $\mathbb{D}_{\text{pw}}\mathcal{C}^\infty \rightarrow \mathbb{D}_{\text{pw}}\mathcal{C}^\infty$

$$D = f_{\mathbb{D}} + \sum_{t \in T} D_t \quad \mapsto \quad D_M := (f_M)_{\mathbb{D}} + \sum_{t \in T \cap M} D_t$$

- ▶ **Multiplication** well defined (Fuchssteiner multiplication)
- ▶ **Evaluation** at $t \in \mathbb{R}$: $D(t^-) := f(t^-)$, $D(t^+) := f(t^+)$
- ▶ **Impulses** at $t \in \mathbb{R}$: $D[t] := \begin{cases} D_t, & t \in T \\ 0, & t \notin T \end{cases}$
- ▶ **Well defined unique antiderivative** $G = \int_{0^-} F$, i.e. $G(0^-) = 0$ and $G' = F$

Examples:

$$\begin{array}{llll} \delta_{[0, \infty)} = \delta, & \delta[0] = \delta & \delta(t \pm) = 0 \quad \forall t & \int_{0^-} \delta = (\mathbb{1}_{[0, \infty)})_{\mathbb{D}} \\ \delta_{(0, \infty)} = 0, & \delta[t] = 0 \quad \forall t \neq 0 & \delta^2 = 0 & \end{array}$$

ITP-solutions

Theorem (cf. TRENN 2012)

Let (E, A) , then $\forall X^0 \in \mathbb{D}_{\text{pw}\mathcal{C}^\infty}^n$ and $\forall U \in \mathbb{D}_{\text{pw}\mathcal{C}^\infty}^m$ there is a **unique** $X \in \mathbb{D}_{\text{pw}\mathcal{C}^\infty}^n$ satisfying

$$\begin{aligned} X_{(-\infty, 0)} &= X^0_{(-\infty, 0)} \\ (E\dot{X})_{[0, \infty)} &= (AX + BU)_{[0, \infty)} \end{aligned} \tag{ITP}$$

Explicit solution formula

$$X(t^+) = e^{A^{\text{diff}} t} \Pi_{(E, A)} X^0(0^-) + e^{A^{\text{diff}} t} \int_{0^-}^{t^+} e^{-A^{\text{diff}} \cdot} B^{\text{diff}} U - \sum_{i=0}^{\nu-1} (E^{\text{imp}})^i B^{\text{imp}} U^{(i)}(t^+)$$

and for $U = 0$ (or $B = 0$)

$$X(0^+) = \Pi_{(E, A)} X^0(0^-) \quad X[0] = \sum_{i=0}^{\nu-2} (E^{\text{imp}})^{i+1} X^0(0^-) \delta^{(i)}$$

Unique jump

$$E\dot{x} = Ax, \quad x(t_0^-) = x_0 \in \mathbb{R}^n$$

Unique jump

$$x(t_0^-) \mapsto x(t_0^+) = \Pi_{(E,A)} x(t_0^-)$$

Why no other jump rule? \leftrightarrow handwritten notes ...

Equivalent jump rules, cf. COSTANTINI, TRENN & VASCA 2013; FRASCA ET AL. 2010

The following jump rules are equivalent:

- ▶ Consistency projector based on Wong sequences and QWF (TRENN 2012)
- ▶ Passivity based energy minimization (FRASCA ET AL. 2010)
- ▶ Conservation of charge/flux (SESHU & BALABANIAN 1964)
- ▶ Laplace transform approach (OPAL & VLACH 1990)

Index of a regular DAE and solution properties

$$E\dot{x} = Ax + Bu, \quad (E, A) \simeq \left(\begin{bmatrix} I & \\ & N \end{bmatrix}, \begin{bmatrix} J & \\ & I \end{bmatrix} \right)$$

Definition (Index)

Index of regular $(E, A) :=$ **nilpotency** index of N in QWF

Theorem (Index and Diracs)

$\exists x_0 \in \mathbb{R}^n$ such that $x[t_0] \neq 0 \iff$ **index** of $(E, A) > 1$

Reminder: $x[t_0] = - \sum_{i=0}^{\nu-2} (E^{\text{imp}})^{i+1} x_0 \delta_{t_0}^{(i)}, \quad E^{\text{imp}} = T \begin{bmatrix} 0 & 0 \\ 0 & N \end{bmatrix} T^{-1}$

Remark (Index and input derivatives)

Solution x depends on **derivatives of u** \implies **index > 1**

Index 1

Conclusion

Index 1 \implies no Diracs in response to inconsistent initial values and discontinuous inputs

$$\text{Index 1: } \begin{cases} E\dot{x} = Ax + Bu \\ y = Cx + Du \end{cases} \iff \begin{cases} \dot{x} = A^{\text{diff}}x + B^{\text{diff}}u \\ y = Cx + (D - CB^{\text{imp}})u \end{cases} \quad x(0^+) \in \text{im } \Pi_{(E,A)}$$

Theorem (Index 1 characterization)

(E, A) with singular and square E is index 1 (i.e. $N = 0$ in QWF)

$$\iff \mathcal{V}_1 \cap \mathcal{W}_1 = A^{-1}(\text{im } E) \cap \ker E = \{0\}$$

$$\iff \mathcal{V}_1 \oplus \mathcal{W}_1 = \mathbb{R}^n$$

$$\iff \deg \det(sE - A) = \text{rank } E$$

$$\iff A_{22} \text{ is invertible where } (E, A) \simeq \left(\begin{bmatrix} I & 0 \\ 0 & 0 \end{bmatrix}, \begin{bmatrix} A_{11} & A_{12} \\ A_{21} & A_{22} \end{bmatrix} \right)$$

$$\iff \begin{bmatrix} E_1 \\ A_2 \end{bmatrix} \text{ is invertible, where } (E, A) \simeq \left(\begin{bmatrix} E_1 \\ 0 \end{bmatrix}, \begin{bmatrix} A_1 \\ A_2 \end{bmatrix} \right) \text{ with } E_1 \text{ full row rank}$$

Summary

$$E\dot{x} = Ax + Bu, \quad x(t_0^-) = x_0$$

▶ Smooth solutions

- ▶ Explicit solution formula:

$$x(t) = e^{A^{\text{diff}}(t-t_0)} \Pi_{(E,A)} x_0 + \int_{t_0}^t e^{A^{\text{diff}}(t-s)} B^{\text{diff}} u(s) ds - \sum_{i=0}^{\nu-1} (E^{\text{imp}})^i B^{\text{imp}} u^{(i)}(t)$$

- ▶ Solution decomposition according to $\mathcal{V}_* \oplus \mathcal{W}_*$: $x = x^{\text{diff}} \oplus x^{\text{imp}}$ with
 $\dot{x}^{\text{diff}} = A^{\text{diff}} x^{\text{diff}} + B^{\text{diff}} u$ and $E^{\text{imp}} \dot{x}^{\text{imp}} = x^{\text{imp}} + B^{\text{imp}} u$

▶ Inconsistent initial values

- ▶ Real world applications motivate presence of Dirac delta
- ▶ Standard distributional solutions not suitable for ITP
- ▶ **Piecewise-smooth distributions** are suitable

▶ Distributional solution theory

- ▶ Existence and uniqueness for ITP
- ▶ **Unique jump** rule for inconsistent initial values
- ▶ **Index** and solution properties