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The one-step-map for switched singular systems in discrete-time

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Supported by NAFOSTED project 101.01-2017.302 and by NWO Vidi grant 639.032.733.

Siegmundsburg Workshop, Elgersburg, Thursday, 20 February 2020, 17:00

System class and motivation

$$E_{\sigma(k)}x(k+1) = A_{\sigma(k)}x(k) \quad (\text{SSS})$$

- › $\sigma : \mathbb{N} \rightarrow \{1, 2, \dots, n\}$ **switching signal**
- › $E_1, E_2, \dots, E_n, A_1, A_2, \dots, A_n \in \mathbb{R}^{n \times n}$ with E -matrix **singular**
- › $x : \mathbb{N} \rightarrow \mathbb{R}^n$ state

Motivation

- › Leontief economic model (*Luenberger 1977*)
- › discretization of continuous-time time-varying DAEs
- › sampled feedback loop for descriptor systems

Simple question

What can we say about existence and uniqueness of solutions?

Small excursion to continuous time

$$E_\sigma \dot{x} = A_\sigma x$$

Theorem (Existence and uniqueness in continuous time, *Trenn 2012*)

Assume (E_i, A_i) are **regular**, i.e. $\det(sE_i - A_i)$ is not the zero polynomial.

Then for any past trajectory $x^0(\cdot)$ and any $t_0 \in \mathbb{R}$ there **exists unique** $x(\cdot)$ such that

$$\begin{aligned} x_{(-\infty, t_0)} &= x^0_{(-\infty, t_0)} \\ (E_\sigma \dot{x})_{[t_0, \infty)} &= (A_\sigma x)_{[t_0, \infty)} \end{aligned}$$

In particular, solution behavior is **causal** w.r.t. to the switching signal.

Distributional solution framework necessary

Above solution result only holds when solution space is enlarged to allow for jumps and **Dirac impulses**.

A simple example

$$E_{\sigma(k)}x(k+1) = A_{\sigma(k)}x(k) \quad (\text{SSS})$$

Example

Consider (SSS) with

$$E_1 = \begin{bmatrix} 1 & 0 \\ 0 & 0 \end{bmatrix}, \quad A_1 = I \quad \text{and} \quad E_2 = \begin{bmatrix} 0 & 0 \\ 0 & 1 \end{bmatrix}, \quad A_2 = I$$

Nonswitched solution behavior

$$\begin{aligned} \sigma \equiv 1 : \quad & \left. \begin{aligned} x_1(k+1) &= x_1(k) \\ 0 &= x_2(k) \end{aligned} \right\} \rightsquigarrow x(k) = \begin{pmatrix} c_1 \\ 0 \end{pmatrix} \quad \forall k \in \mathbb{N} \\ \sigma \equiv 2 : \quad & \left. \begin{aligned} 0 &= x_1(k) \\ x_2(k+1) &= x_2(k) \end{aligned} \right\} \rightsquigarrow x(k) = \begin{pmatrix} 0 \\ c_2 \end{pmatrix} \quad \forall k \in \mathbb{N} \end{aligned}$$

A simple example

$$E_{\sigma(k)}x(k+1) = A_{\sigma(k)}x(k) \quad (\text{SSS})$$

Example

Consider (SSS) with

$$E_1 = \begin{bmatrix} 1 & 0 \\ 0 & 0 \end{bmatrix}, \quad A_1 = I \quad \text{and} \quad E_2 = \begin{bmatrix} 0 & 0 \\ 0 & 1 \end{bmatrix}, \quad A_2 = I$$

Switched solution behavior $\sigma(k) = \begin{cases} 1, & k < k_s \\ 2, & k \geq k_s \end{cases}$

For $k < k_s$ we have $x(k) = \begin{pmatrix} c_1 \\ 0 \end{pmatrix}$ and for $k = k_s - 1$ also $x_1(k_s) = x_1(k_s - 1) = c_1$

BUT: For $k = k_s$ also $0 = x_1(k_s)$, hence $c_1 = 0$ necessary!

Furthermore $x_2(k_s)$ not constraint by mode 1 $\rightsquigarrow x_2(k) = c_2$ for all $k \geq k_s$

$\rightsquigarrow x(k) = \begin{pmatrix} 0 \\ 0 \end{pmatrix}$ for $k < k_s$ and $x(k) = \begin{pmatrix} 0 \\ c_2 \end{pmatrix}$ for $k \geq k_s$

Observations from example

$$E_{\sigma(k)}x(k+1) = A_{\sigma(k)}x(k) \quad (\text{SSS})$$

No existence and uniqueness of solutions!

- › Not all solutions from the past can be extended to a global solution
- › Single initial value leads to multiple solutions in the future
- › Loss of causality w.r.t. to switching signal

Definition

(SSS) is called **causal w.r.t. the switching signal** $:\Leftrightarrow \forall \sigma, \tilde{\sigma} \forall x(\cdot)$ sol. for $\sigma \forall \tilde{k} \in \mathbb{N}$:

$$\sigma(k) = \tilde{\sigma}(k) \quad \forall k \leq \tilde{k} \quad \Longrightarrow \quad \exists \tilde{x}(\cdot) \text{ sol. for } \tilde{\sigma} : \tilde{x}(k) = x(k) \quad \forall k \leq \tilde{k}$$

Example not causal w.r.t. the switching signal: Let $\sigma \equiv 1$, $\tilde{\sigma}(k) = \begin{cases} 1, & k < k_s \\ 2, & k \geq k_s \end{cases}$
 \rightsquigarrow no solution \tilde{x} with $\tilde{x}(k) = c_1 = x(k) \neq 0$ for $k < k_s$.

Causality and One-Step-Map

$$E_{\sigma(k)}x(k+1) = A_{\sigma(k)}x(k) \quad (\text{SSS})$$

Question

When is (SSS) causal w.r.t. the switching signal?

More specifically: When is $x(k+1)$ uniquely defined for all $x(k)$, $\sigma(k)$ and $\sigma(k+1)$?

In other words: Is there a **one-step-map** $\Phi_{i,j} \in \mathbb{R}^{n \times n}$, $i, j \in \{1, 2, \dots, n\}$ such that

$$\forall \text{ sol. } x(\cdot) \text{ of (SSS) : } x(k+1) = \Phi_{\sigma(k+1), \sigma(k)}x(k)$$

Regularity and index

Theorem (Quasi-Weierstrass Form)

(E, A) is regular $\iff \exists S, T$ invertible with

$$(SET, SAT) = \left(\begin{bmatrix} I & 0 \\ 0 & N \end{bmatrix}, \begin{bmatrix} J & 0 \\ 0 & I \end{bmatrix} \right) \quad (\text{QWF})$$

where N is nilpotent

Definition

(E, A) has **index-1** $:\iff N = 0$ in (QWF)

Index-1 (together with regularity) is also called:

- › causal
- › admissible
- › impulse-free

Index-1 characterization

Theorem (see e.g. *Griepentrog & März 1986*)

(E, A) is regular and index-1

$$\iff \mathcal{S} \oplus \ker E = \mathbb{R}^n, \text{ where } \mathcal{S} := A^{-1}(\text{im } E) := \{\xi \in \mathbb{R}^n \mid A\xi \in \text{im } E\}$$

$$\iff \mathcal{S} \cap \ker E = \{0\}$$

Furthermore, $T = [T_1, T_2]$ and $S = [ET_1, AT_2]^{-1}$ with $\text{im } T_1 = \mathcal{S}$ and $\text{im } T_2 = \ker E$:

$$(SET, SAT) = \left(\begin{bmatrix} I & 0 \\ 0 & 0 \end{bmatrix}, \begin{bmatrix} J & 0 \\ 0 & I \end{bmatrix} \right) \quad (\text{QWF})$$

Corollary

$Ex(k+1) = Ax(k)$ being regular + index-1 has **unique solution** with $x(0) = x_0 \in \mathbb{R}$

$$\iff x_0 \in \mathcal{S}$$

In fact, $x(k+1) = \Phi_{(E,A)}x(k)$ with $\Phi_{(E,A)} := T \begin{bmatrix} J & 0 \\ 0 & 0 \end{bmatrix} T^{-1}$

Is this the sought one-step map already?

Attention

$\Phi_{(E,A)}$ is one-step-map for $Ex(k+1) = Ax(k)$

BUT: Only true when system is active for at least **two** time-steps:

$$Ex(1) = Ax(0) \implies x(1) \in E^{-1}(Ax(0)) = \{\Phi_{(E,A)}x(0)\} + \ker E$$

$$Ex(2) = Ax(1) \implies x(1) \in A^{-1}(Ex(2)) \subseteq \mathcal{S}$$

Hence, invoking $\mathcal{S} \cap \ker E = \{0\}$,

$$Ex(1) = Ax(0) \quad \wedge \quad Ex(2) = Ax(1) \quad \implies \quad x(1) = \Phi_{(E,A)}x(0)$$

↪ **Not suitable for switched systems!**

Both modes in Example were regular+index-1, but no one-step-map exists!

Problem seems to be overlooked in the literature so far!

A key definition

$$E_{\sigma(k)}x(k+1) = A_{\sigma(k)}x(k) \quad (\text{SSS})$$

Definition

(SSS) or $\{(E_1, A_1), (E_2, A_2), \dots, (E_n, A_n)\}$ is called (jointly) **index-1** $:\Leftrightarrow$

$$\mathcal{S}_i \cap \ker E_j = \{0\} \quad \forall i, j \in \{1, 2, \dots, n\}, \quad \mathcal{S}_i := A_i^{-1}(\text{im } E_i)$$

- › Clearly ($i = j$) each pair (E_i, A_i) must be index-1
- › In general, (E_j, A_i) is **not index-1** (not even regular)

Example

$$E_1 = \begin{bmatrix} 1 & 0 \\ 0 & 0 \end{bmatrix}, \quad A_1 = I \quad \rightsquigarrow \quad \ker E_1 = \text{span} \left\{ \begin{pmatrix} 0 \\ 1 \end{pmatrix} \right\}, \quad \mathcal{S}_1 = A_1^{-1}(\text{im } E_1) = \text{span} \left\{ \begin{pmatrix} 1 \\ 0 \end{pmatrix} \right\}$$

$$E_2 = \begin{bmatrix} 0 & 0 \\ 0 & 1 \end{bmatrix}, \quad A_2 = I \quad \rightsquigarrow \quad \ker E_2 = \text{span} \left\{ \begin{pmatrix} 1 \\ 0 \end{pmatrix} \right\}, \quad \mathcal{S}_2 = A_2^{-1}(\text{im } E_2) = \text{span} \left\{ \begin{pmatrix} 0 \\ 1 \end{pmatrix} \right\}$$

Clearly, $\mathcal{S}_i \cap \ker E_j \neq \{0\}$ for $i \neq j$.

The one-step-map

$$E_{\sigma(k)}x(k+1) = A_{\sigma(k)}x(k), \quad x(0) = x_0 \quad (\text{SSS})$$

Theorem (Anh, Linh, Thuan, T; CDC 2019)

Assume (SSS) is (jointly) index-1. Then $\forall \sigma \forall x_0 \in \mathbb{R}^n$:

$$x(\cdot) \text{ solves (SSS)} \iff x_0 \in \mathcal{S}_{\sigma(0)} \wedge x(k+1) = \Phi_{\sigma(k+1), \sigma(k)}x(k)$$

where

$$\Phi_{i,j} := \Pi_{\mathcal{S}_i}^{\ker E_j} \cdot \Phi_{(E_j, A_j)}$$

and $\Pi_{\mathcal{S}_i}^{\ker E_j}$ is the projector onto \mathcal{S}_i along $\ker E_j$.

Skip proof

Proof idea

$$x(k+1) = \Phi_{\sigma(k+1),\sigma(k)} x(k) \quad \text{with} \quad \Phi_{i,j} := \Pi_{\mathcal{S}_i}^{\ker E_j} \cdot \Phi_{(E_j, A_j)}$$

Lemma

For any subspace $\mathcal{V}, \mathcal{W} \subseteq \mathbb{R}^n$ it holds that

$$\mathcal{V} \oplus \mathcal{W} = \mathbb{R}^n \quad \implies \quad \mathcal{V} \cap (\{z\} + \mathcal{W}) = \{\Pi_{\mathcal{V}}^{\mathcal{W}} z\}$$

- › index-1 $\implies \mathcal{S}_i \oplus \ker E_j = \mathbb{R}^n \rightsquigarrow \Pi_{\mathcal{S}_i}^{\ker E_j}$ well defined
- › $E_{\sigma(0)} x(1) = A_{\sigma(0)} x(0) \implies x(0) \in \mathcal{S}_{\sigma(0)}$
- › Show by induction that $x(k) \in \mathcal{S}_{\sigma(k)} \implies \exists! x(k+1) \in \mathcal{S}_{\sigma(k+1)}$
 - $E_{\sigma(k)} x(k+1) = A_{\sigma(k)} x(k) \implies x(k+1) \in \{\Phi_{(E_{\sigma(k)}, A_{\sigma(k)})} x(k)\} + \ker E_{\sigma(k)}$
 - $E_{\sigma(k+1)} x(k+2) = A_{\sigma(k+1)} x(k+1) \implies x(k+1) \in A_{\sigma(k+1)}^{-1} (\text{im } E_{\sigma(k+1)}) = \mathcal{S}_{\sigma(k+1)}$
 - $\stackrel{\text{Lemma}}{\implies} x(k+1) = \Pi_{\mathcal{S}_{\sigma(k+1)}}^{\ker E_{\sigma(k)}} \Phi_{(E_{\sigma(k)}, A_{\sigma(k)})} x(k)$

Necessity of index-1 assumption

$$E_{\sigma(k)}x(k+1) = A_{\sigma(k)}x(k), \quad x(0) = 0 \quad (\text{SSS})$$

Theorem

$\forall \sigma \ x(1) = 0$ is only solution of (SSS) for $k = 0, 1$
 $\implies \mathcal{S}_i \cap \ker E_j = \{0\}$ for $i, j \in \{1, 2, \dots, n\}$

Proof sketch:

- › $k = 0$: $E_j x(1) = A_j x(0) = 0 \iff x(1) \in \ker E_j$
- › $k = 1$: $E_i x(2) = A_i x(1) \iff x(1) \in \mathcal{S}_i$
- › $x(1) = 0$ is only solution $\implies \ker E_j \cap \mathcal{S}_i = \{0\}$

Summary

$$E_{\sigma(k)}x(k+1) = A_{\sigma(k)}x(k) \quad (\text{SSS})$$

- › Simple example shows that **index-1 of each mode** is **not sufficient for existence and uniqueness** of solutions
- › (SSS) is **index-1** : $\iff A_i^{-1}(\text{im } E_i) \cap \ker E_j = \{0\} \quad \forall i, j \in \{1, 2, \dots, n\}$
- › (SSS) index-1 \implies existence of one-step-map $\Phi_{i,j}$ such that

$$x(k+1) = \Phi_{\sigma(k+1), \sigma(k)}x(k)$$

- › Unique solvability \implies index-1 of (SSS)

Extensions

- › Explicit calculation of $\Phi_{i,j}$ (without QWF)
- › Extension to inhomogeneous case
- › Stability analysis via joint spectral radius