

# Zeno-like behavior in coupled systems of switched DAEs and PDEs

#### Stephan Trenn

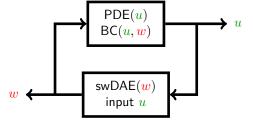
Jan C. Willems Center for Systems and Control University of Groningen, Netherlands

Joint work with **Damla Kocuglu** and **Raul Borsche**AG Technomathematik. TU Kaiserslautern





# Setup: Coupling of PDE and swDAE



Motivation: Human blood flow

PDE: Blood flow in vessels

**swDAE**: Heart (valve = switch)



### Extremely simplified linear model

#### swDAE heart model

Valve open 
$$(p(t) > P(t, 0))$$

$$\begin{split} \dot{p} &= -q \\ \dot{q} &= p \\ Q(t,0) &= q(t) \end{split}$$

Valve closed 
$$(p(t) \le P(t, 0))$$

$$\dot{p} = -q$$

$$q = 0$$

$$Q(t, 0) = q(t)$$

$$P(t,x)$$

$$Q(t,x)$$

#### PDE vessel model

$$P_t + Q_x = 0$$
$$Q_t + c^2 P_x = 0$$

Domain:  $t \ge 0$ ,  $x \ge 0$ Initial conditions:

$$P(0,x) = P_0(x), \quad Q(0,x) = Q_0(x)$$



# Decoupling of PDE

Applying coordinate transformation  $\binom{v_1}{v_2} = \left[ \begin{smallmatrix} 1 & 1 \\ -c & c \end{smallmatrix} \right]^{-1} \left( \begin{smallmatrix} P \\ Q \end{smallmatrix} \right)$  yields **decoupled** PDEs

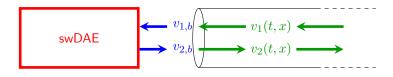
$$\begin{vmatrix} v_{1t} - cv_{1x} = 0 \\ v_{2t} + cv_{2x} = 0 \end{vmatrix}$$

#### Unique solution

$$v_1(t,x) = v_1^0(ct+x) \qquad \qquad \text{Output: } v_{1,b}(t) := v_1(t,0)$$
 
$$v_2(t,x) = \begin{cases} v_2^0(x-ct), & t \leq x/c \\ v_{2,b}(t-x/c), & t > x/c \end{cases} \qquad \text{Input: } v_{2,b}(t) := v_2(t,0)$$



### Combining swDAE with decoupled PDE

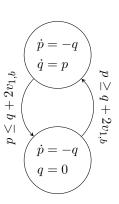


#### swDAE model

$$\begin{array}{ll} \textbf{Valve open } (p>v_{1,b}+v_{2,b}) & \textbf{Valve closed } (p\leq v_{1,b}+v_{2,b}) \\ & \dot{p}=-q & \dot{p}=-q \\ & \dot{q}=p & q=0 \\ & v_{2,b}=q+v_{1,b} & v_{2,b}=q+v_{1,b} \end{array}$$

 $\hookrightarrow$  open loop analysis possible



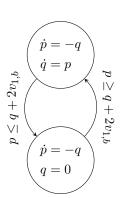


#### Euler steps with fixed step-size

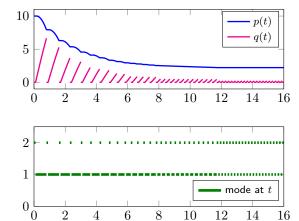
Given: 
$$w_k^- = \begin{pmatrix} p_k^- \\ q_k^- \end{pmatrix}$$
 state value at  $t_k^ u_k$  input value at  $t_k$   $u_{k+1}$  input value at  $t_{k+1}$   $m_k^-$  active mode at  $t_k^-$ 

$$\begin{split} \textbf{Step 1: Switching?} \ \exists m: g_{m_k^-,m}(w_k^-,u_k) \leq 0? \\ \text{YES: } m_k^+ := m, \ w_k^+ := \Pi_{m_k^+}w_k^- \\ \text{NO: } m_k^+ := m_k^-, \ w_k^+ := w_k^- \end{split}$$

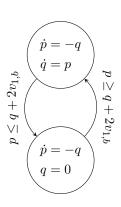
**Step 2:** Euler Step 
$$w_{k+1}^- = ES_{m_k^+}(w_k^+, u_k, u_{k+1})$$



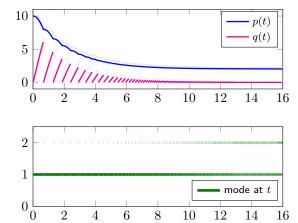
Results for  $p(0^-) = 10$ ,  $q(0^-) = 10$ ,  $v_{1,b} = 1$  time step size = 0.1



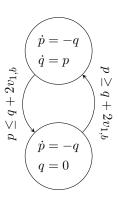




Results for  $p(0^-)=10$ ,  $q(0^-)=10$ ,  $v_{1,b}=1$  time step size =0.01







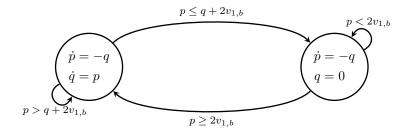
#### Major numerical problems

For exact solution:

- 1. Leaving Mode 2 immediately after entering
- 2. Zeno-like behavior
  - ightarrow no upper bound on switching frequency
  - $\rightarrow$  any adaptive step size method breaks down
- 3. What happens after Zeno?

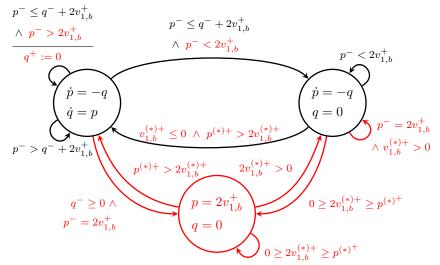
Setup

# Refining swDAE model - going beyond Zeno



Setup

# Refining swDAE model - going beyond Zeno



Inspired by: Zhen et al.: Beyond Zeno: Get on with it!, HSCC 2006



# Guards relaxation for numerical integration

#### Key features of refinement

- Multiple mode changes at one time instant avoided
- Sliding mode (after zeno) explicitly visible

#### Unresolved problem

Zeno behavior sill present and leads to numerical problems

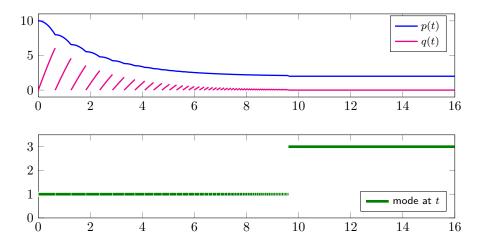
#### Numerical treatmant

Relax all ingoing transition towards a sliding mode



Setup

### Improved numerical simulation



#### Conclusion

Setup

#### Numerical challenges in coupling swDAEs and PDEs

- Identify inputs/outputs in the coupling  $\rightarrow$  Coordinate transformations
- Refine swDAE-model by introducing additional jump maps and Zeno states
- Relax guards to avoid accumulation of switching times
- Adaptive time stepping near Zeno
- Guards depending on derivatives of input

#### Theoretical challenges

- > Solution framework which allows for Zeno-solution
- Dirac impulses (derivatives of jumps)
- > Dynamics in Zeno-state