

Solution theory for switched differential-algebraic equations

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Solution of a pure DAE



$$N\dot{x} = x + f$$

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$$\begin{aligned} N\dot{x} &= x + f \\ \xrightarrow{\frac{d}{dt} \& N \cdot} \quad N^2\ddot{x} &= N\dot{x} + Nf' \end{aligned}$$

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Theorem (Unique solution of a pure DAE)

Unique solution of the pure DAE $N\dot{x} = x + f$ is

$$x = - \sum_{i=0}^{d-1} N^i f^{(i)}$$

Regularity and similarity

Definition (Regularity)

(E, A) is called **regular** : \Leftrightarrow

- 1) **Existence:** $\forall f \in \mathcal{C}^\infty \exists$ solution x of (DAE) and
- 2) **Uniqueness:** $\forall f \in \mathcal{C}^\infty \forall$ solutions $x_1, x_2 \forall t_0 \in \mathbb{R}$:

$$x_1(-\infty, t_0) = x_2(-\infty, t_0) \Rightarrow x_1 = x_2$$

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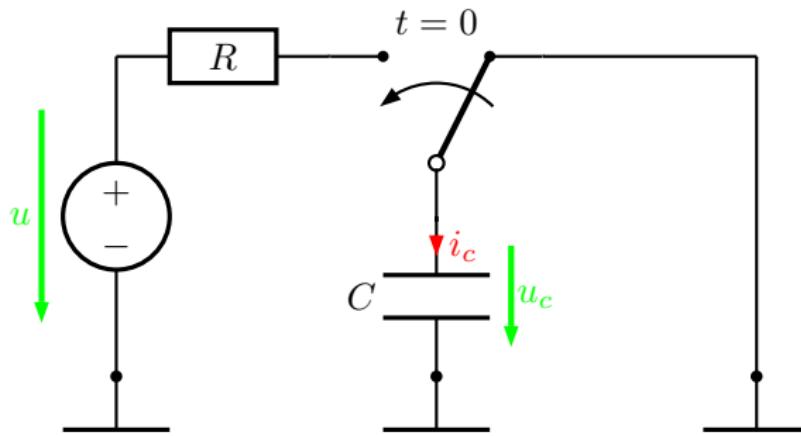
Similarity

For S, T invertible matrices:

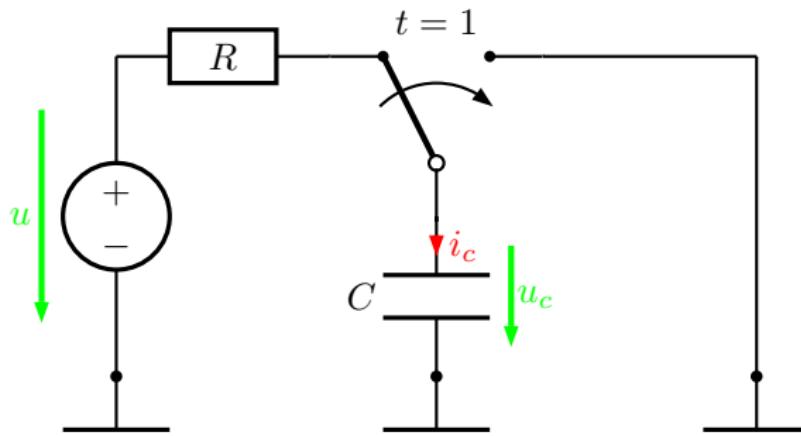
$$E\dot{x} = Ax + f \quad \stackrel{x=Tz}{\Leftrightarrow} \quad SET\dot{z} = SATz + Sf$$

Write: $(E, A) \cong (SET, SAT)$

A simple circuit example



A simple circuit example



Basic ideas of distributions



Distributions - overview

- Generalized functions
- Arbitrarily often differentiable
- Dirac impulse δ is “derivative” of step function $\mathbb{1}_{[0,\infty)}$
- Formally defined by Schwartz 1950

Formal definition of distributions



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$$f \in L_{1,\text{loc}}(\mathbb{R} \rightarrow \mathbb{R}): \quad f_{\mathbb{D}} : \mathcal{C}_0^\infty \rightarrow \mathbb{R}, \quad \varphi \mapsto \int_{\mathbb{R}} \varphi(t) f(t) dt$$

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Definition (Derivative)

$D'(\varphi) := -D(\varphi')$

Dirac impulse at $t_0 \in \mathbb{R}$

$\delta_{t_0} : \mathcal{C}_0^\infty \rightarrow \mathbb{R}, \varphi \mapsto \varphi(t_0)$

Desired properties of distributional restriction



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$$D_M = \sum_{i \in \mathbb{N}} D_{M_i}, \quad D_{M_1 \cup M_2} = D_{M_1} + D_{M_2}$$

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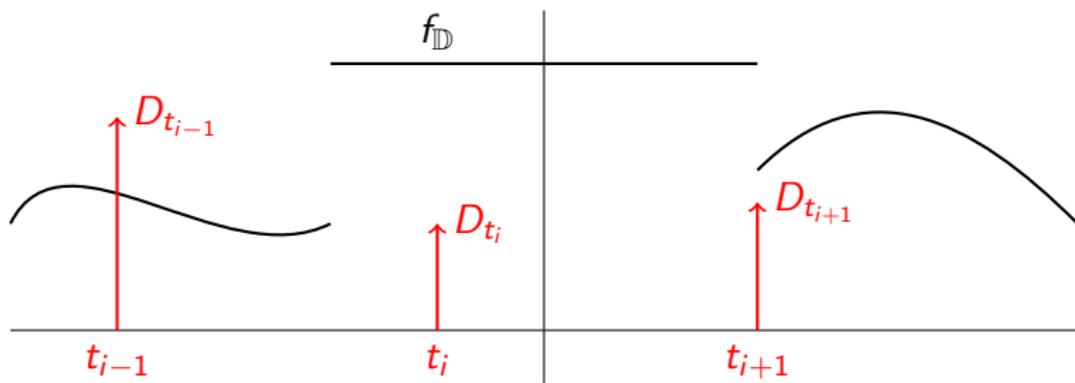
and additionally,

$$(D_{M_1})_{M_2} = 0$$

Piecewise smooth distributions

Definition (Piecewise smooth distributions $\mathbb{D}_{\text{pw}\mathcal{C}^\infty}$)

$$\mathbb{D}_{\text{pw}\mathcal{C}^\infty} = \left\{ f_{\mathbb{D}} + \sum_{t \in T} D_t \mid \begin{array}{l} f \in \mathcal{C}_{\text{pw}}^\infty, \\ T \subseteq \mathbb{R} \text{ locally finite,} \\ \forall t \in T : D_t = \sum_{i=0}^{n_t} a_i^t \delta_t^{(i)} \end{array} \right\}$$



Some results for DAE-regularity



Theorem (ODEs and pure DAEs are DAE-regular)

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If (E, A) is DAE-regular, then $(SET, SAT - SET')$ is DAE-regular for invertible (time-varying) matrices S and T .

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Theorem (Switching and regularity)

If (E_i, A_i) is DAE-regular for all $i \in \mathbb{Z}$ and $\{ t_i \in \mathbb{R} \mid i \in \mathbb{Z} \}$ is ordered and locally finite, then $(\sum_{i \in \mathbb{Z}} E_{i[t_i, t_{i+1}]}, \sum_{i \in \mathbb{Z}} A_{i[t_i, t_{i+1}]})$ is DAE-regular.

Some questions



- What is the “right” definition for controllability?
- Using impulses for control
- Impulse avoidance with feedback

Summary



- Motivation to study distributional DAEs
 - Jumps in inhomogeneity
 - Inconsistent initial values
 - Switching
- Problems with a distributional approach
 - Restriction in general not possible
 - Multiplication with piecewise-smooth coefficients
 - Solution: piecewise-smooth distributions
- Solution theory for distributional DAEs
 - New definition: DAE-regularity
 - Feasible for switched DAEs